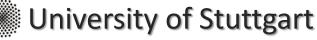
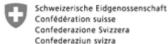


21st ISES Annual Meeting | Baltimore | Oct 23-27, 2011



Institute of Energy Economics and the Rational Use of Energy











### Outline



1. Objectives

2. dynamiCROP Model

3. Parameterization

4. Conclusions

Structure & Features
Multicrop Aspects
Environmental Fate
Human Exposure

Evaluation
Compartments
Other Aspects
Regression Model

## Objectives



#### Needs ...

- Pesticides residues in various food crops
- Species-specific plant characteristics
- Regression for use in spatial models

#### **But ...**

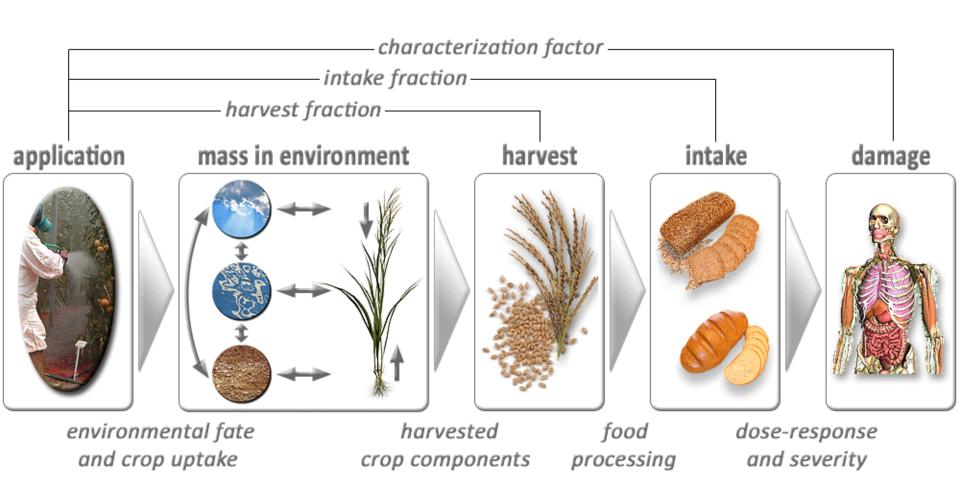
- No existing multicrop model
- No flexibility for crop-specific aspects
- No model simple enough for integration

#### Thus ...

- Dynamic crop-specific multicrop model
- Flexible analytical mass balance solution
- System analysis and parameterization

### dynamiCROP – Structure





### dynamiCROP – Features



#### **System**

- Dynamic over time, analytical solution
- Flexible set of connected compartments
- Intermittent character of rain considered

#### **Crop aspects**

- Protected (hull) and unprotected fruit
- Exchange between surface and interior
- Logistic growth for stem and root
- Complex growth for leaf area and fruit
- Crop-specific intake fractions

#### **Exposure**

Crop-specific food processing

### Multicrop Aspects – Crops





- Wheat (68% of cereals)
- Paddy rice (97% of paddy cereals)
- **Tomato** (15% of herbaceous vegetables)
- Apple (13% of fruit trees)
- Lettuce (14% of leafy vegetables)
- Potato (51% of roots and tubers)

45% of global vegetal consumption

### Multicrop Aspects – Criteria



	Residues	Characteristics	Consumed	Models/Experiments
Wheat	medium	grass-like	grain	√/√
Paddy rice	medium	grass-like; paddy water	grain	√ / √
Tomato	high	herbaceous	fruit	✓/✓
Apple	high	tree-like; perennial	fruit	√ / √
Lettuce	high	herbaceous; high adsorption	leaf	✓/✓
Potato	medium	herbaceous	root/stem tuber	√/√

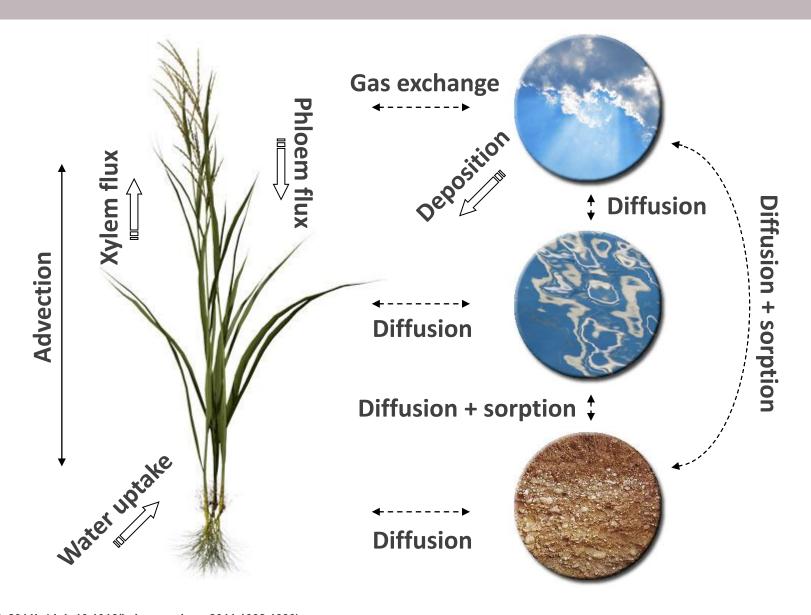


Crop-specific compartment characteristics, processes and food processing considered!

Fantke et al. 2011a (doi: 10.1021/es201989d)

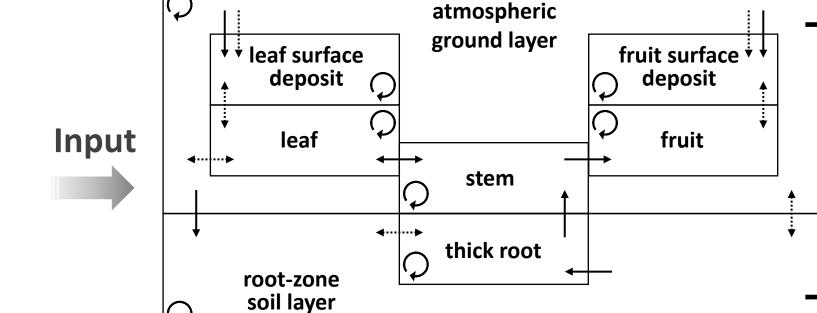
## Physical System





## **Modeled System**





Degradation
Diffusive process
Advective process
System loss

### Mass Balance



#### Mass balance system:

$$\frac{d\vec{m}(t)}{dt} = \mathbf{K} \, \vec{m}(t)$$

$$\mathbf{K} : \text{matrix of rate constants } k \text{ [draw]}$$

$$t : \text{time [d]}$$

 $\vec{m}$ : vector of masses [kg]

constants k [d<sup>-1</sup>]

		air	soil	• • •	leat
<b>K</b> :=	air	$-k_{ m air,total}$	<b>k</b> <sub>air←soil</sub>	•••	$k_{air \leftarrow leaf}$
	soil	$k_{soil\leftarrowair}$	$-k_{ m soil,total}$		0
	•	:		•••	:
	leaf	<b>k</b> <sub>leaf←air</sub>	0	• • •	- k <sub>leaf,total</sub>





### Harvest Fraction residual mass in all harvested crop parts i relative to total applied mass

$$hF = \frac{\sum_{i=1}^{n} m_i(t)}{m_{\text{app}}}$$

hF: harvest fraction [kg<sub>in harvest</sub>/kg<sub>applied</sub>]  $m_i$ : residual mass in compartment i [kg<sub>in harvest</sub>]  $m_{app}$ : total applied mass [kg<sub>applied</sub>] t: harvest time [d]

#### Intake Fraction

### mass taken in via consumption relative to total applied mass

$$iF = hF \times PF$$

iF : intake fraction [kg<sub>intake</sub>/kg<sub>applied</sub>]PF : food processing factor [kg<sub>intake</sub>/kg<sub>in harvest</sub>]

### **Human Exposure**



### Harvest Fraction residual mass in all harvested crop parts i relative to total applied mass

$$hF = rac{\sum_{i=1}^{n} m_i(t)}{m_{\mathrm{app}}}$$

hF: harvest fraction [kg<sub>in harvest</sub>/kg<sub>applied</sub>]  $m_i$ : residual mass in compartment i [kg<sub>in harvest</sub>]  $m_{app}$ : total applied mass [kg<sub>applied</sub>] t: harvest time [d]



#### **Model parameterization**



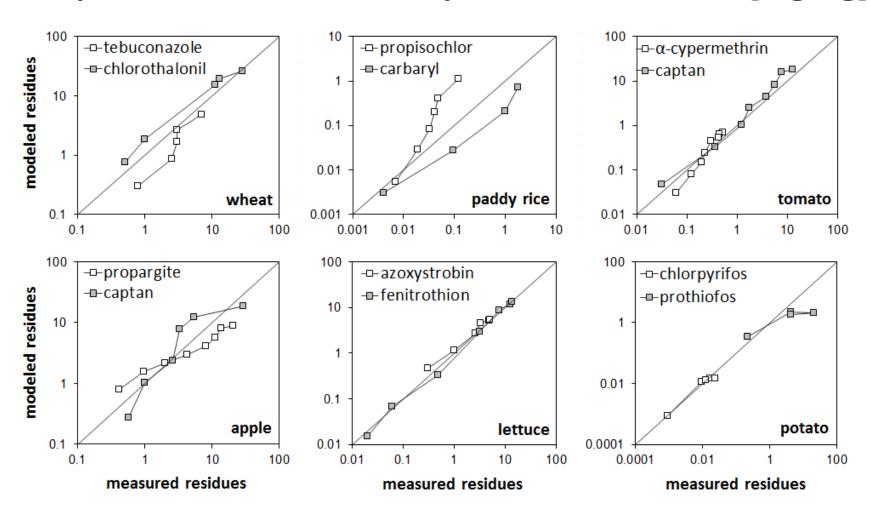
**System Analysis** 

(reducing complex dynamic model by linear combination of different aspects)

### Analysis – Evaluation



#### Comparison of modeled & experimental residues [mg/kg]

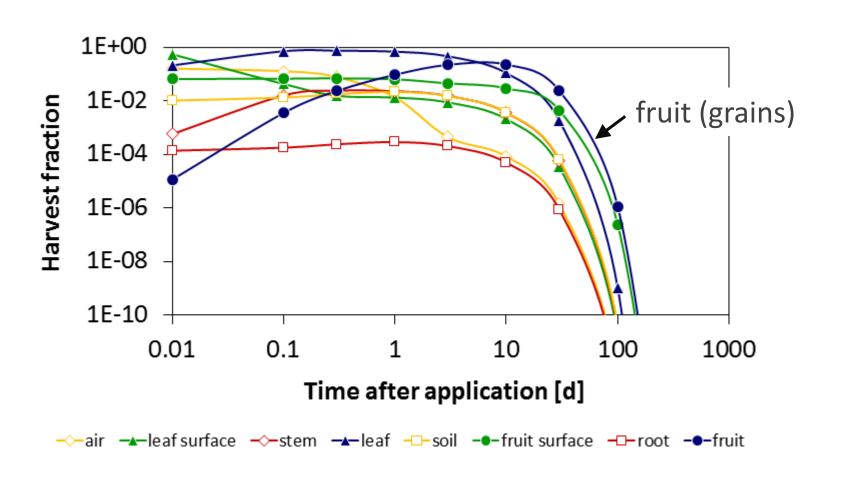


Fantke et al. 2011a (doi: 10.1021/es201989d)

#### •••••

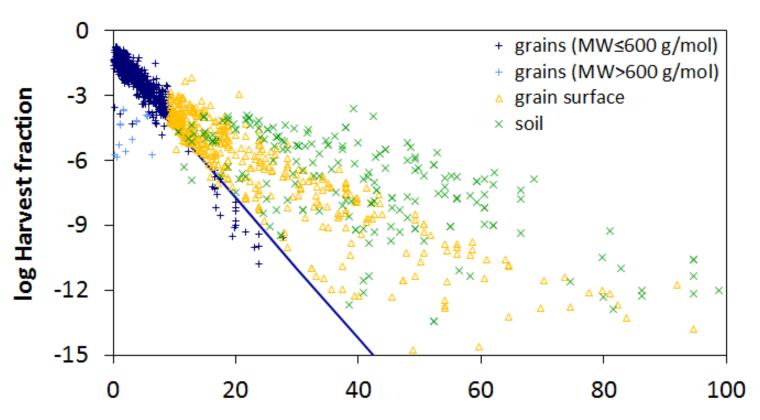
### Analysis – Compartments

#### Example: cyromazine (CAS: 66215-27-8) sprayed on wheat



### Analysis – Other Aspects

#### 385 pesticides sprayed on wheat at 4 different times (n=1540)



Time to harvest / degradation residence time in grains

### Regression – Equation



#### Linear combination

$$hF = hF'_{grain} + hF'_{grain-surface} + hF'_{soil}$$
  $+ hF'_{soil} = hF'_{a,\beta}$  : regression coefficients  $t$  : time to harvest [d]

*hF* : harvest fraction [kg<sub>in harvest</sub>/kg<sub>applied</sub>]

HL: degradation half-life [d]

: degradation residence time [d]

MW: molecular weight [g/mol]

#### with

$$\log(hF'_{\text{grain}}) = \alpha_{\text{grain}} + \beta_{\text{grain}} \frac{t}{HL_{\text{grain}} / \ln(2)} + \beta_{\text{MW}} (MW - MW_0)$$

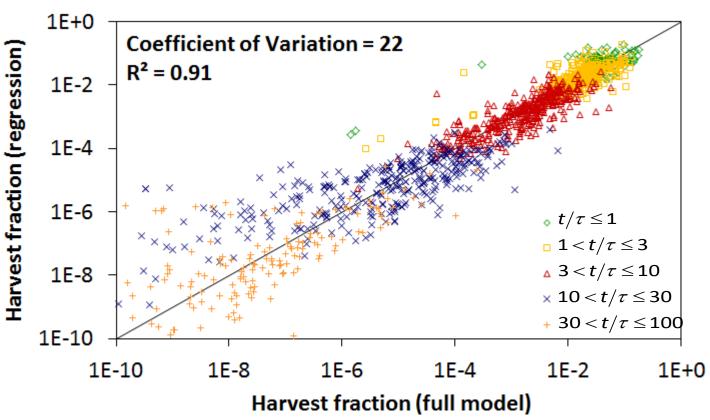
$$\log(hF'_{\text{grain-surface}}) = \alpha_{\text{grain-surface}} + \beta_{\text{grain-surface}} \frac{t}{HL_{\text{grain-surface}}} + \beta_{\text{MW}} (MW - MW_0)$$

$$\log(hF'_{\text{soil}}) = \alpha_{\text{soil}} + \beta_{\text{soil}} \frac{t}{\tau_{\text{soil}}} + \beta_{\text{MW}} (MW - MW_0)$$

### Regression – Results



#### 385 pesticides sprayed on wheat at 4 different times (n=1540)



t: time from application to harvest [d]

 $\tau$ : degradation residence time in grains [d]

### Regression – Other Crops



#### Adoption of regression to other crops requires ...



 Paddy rice (paddy water aspects, Kow, solubility, etc.)

Lettuce (air/leaf exchange aspects,
 Kaw, rain rate, etc.)

Potato (soil aspects, Koc, soil matrix, pH, porosity, etc.)



Adjustment of regression!

### Conclusions



# dynamiCROP full model

- Crop-specific model for characterizing pesticides residues in multiple crops
- Considered crops cover 45% of global vegetal consumption
- Flexible set of compartments and analytical mass balance allow for systematic analysis of system dynamics

#### **Parameterization**

- Regression model for wheat with dependency of only 5 input variables
- Deviation from full model of factor 22 over hF range of 10 order of magnitude

### **Development Team**

Peter Fantke (USTUTT, Germany)
Olivier Jolliet (UMICH, U.S.)
Raphaël Charles (ACW, Switzerland)
Ronnie Juraske (ETHZ, Switzerland)

### Acknowledgements

Stefan Trapp (DTU, Denmark)
Cédric Wannaz (UMICH, U.S.)
Kiyotada Hayashi (AFFRC, Japan)
Stefan Reichenberger (FOOTWAYS, France)
Peter Wieland (BOSCH, Germany)
Shanna Shaked (UMICH, U.S.)

Model: http://dynamicrop.org







